

NI-IMAQ User Manual

Image Acquisition Software for PCI

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About This Manual

NI-IMAQ software is a powerful application programming interface (API) between your image acquisition application and the National Instruments image acquisition (IMAQ) devices for PCI bus computers. This manual explains how to use your NI-IMAQ software.

How to Use the NI-IMAQ Manual Set

To install your software and documentation set, you should begin by reading the NI-IMAQ release notes. Then read Chapter 1, *Introduction*, of *Getting Started with Your IMAQ PCI-1408 and the NI-IMAQ Software for Windows 95/NT*, which contains a flowchart that illustrates the sequence of steps you should take to learn about and get started with NI-IMAQ.

When you are familiar with the material in this manual, you can use the *NI-IMAQ Function Reference Manual*, which contains detailed descriptions of the NI-IMAQ functions.

Organization of This Manual

The NI-IMAQ User Manual is organized as follows:

- Chapter 1, *Introduction to NI-IMAQ*, describes the NI-IMAQ software and lists the application development environments compatible with NI-IMAQ.
- Chapter 2, Fundamentals of Building Windows Applications with NI-IMAQ, describes the fundamentals of creating NI-IMAQ applications for Windows 95 and Windows NT, describes the files used to build these applications, and tells you where to find sample programs.
- Chapter 3, *Software Overview*, describes the classes of NI-IMAQ functions and briefly describes each function.
- Chapter 4, Programming with NI-IMAQ, contains an overview of the NI-IMAQ library, a description of the programming flow of NI-IMAQ, and programming examples.

- The *Customer Communication* appendix contains forms you can use to request help from National Instruments or to comment on our products and manuals.
- The Glossary contains an alphabetical list and description of terms used in this manual, including abbreviations, acronyms, metric prefixes, mnemonics, and symbols.
- The *Index* contains an alphabetical list of key terms and topics in this manual, including the page where you can find each one.

Conventions Used in This Manual

The following conventions are used in this manual:

bold Bold text denotes menus, menu items, or dialog box buttons or options.

bold italic Bold italic text denotes a note, caution, or warning.

italic Italic text denotes emphasis, a cross reference, or an introduction to a

key concept.

italic Italic text in this font denotes that you must supply the appropriate monospace words or values in the place of these items.

Lowercase text in this font denotes text or characters that are to be literally input from the keyboard, sections of code, programming examples, and syntax examples. This font is also used for the proper names of disk drives, paths, directories, programs, subprograms, subroutines, device names, functions, variables, filenames, and extensions, and for statements and comments taken from program code.

Abbreviations, acronyms, metric prefixes, mnemonics, symbols, and terms are listed in the *Glossary*.

monospace

About the National Instruments Documentation Set

The *NI-IMAQ User Manual* is one piece of the documentation set for your system. You could have any of several types of documents, depending on the hardware and software in your system. Use the documents you have as follows:

- Your IMAQ documentation—These documents have detailed information about the IMAQ hardware that plugs into or is connected to your computer. Use these manuals for hardware installation and configuration instructions, hardware specification information, and application hints.
- Software documentation—Examples of software documentation you might have are the LabVIEW and LabWindows®/CVI documentation and the NI-IMAQ documentation. After you have set up your hardware system, use either the application software (LabVIEW or LabWindows/CVI) or the NI-IMAQ documentation to help you write your application. If you have a large and complicated system, it is worthwhile to look through the software documentation before you configure your hardware.

Related Documentation

The following document contains information you may find useful as you read this manual:

• Microsoft Visual C++ User Guide to Programming

Customer Communication

National Instruments wants to receive your comments on our products and manuals. We are interested in the applications you develop with our products, and we want to help if you have problems with them. To make it easy for you to contact us, this manual contains comment and configuration forms for you to complete. These forms are in the *Customer Communication* appendix at the end of this manual.

Introduction to NI-IMAQ



This chapter describes the NI-IMAQ software and lists the application development environments compatible with NI-IMAQ.

About the NI-IMAQ Software

Thank you for buying a National Instruments image acquisition (IMAQ) device for PCI, which includes NI-IMAQ software. NI-IMAQ is a set of functions that controls the National Instruments plug-in IMAQ devices for image acquisition and Real-Time System Integration (RTSI) bus multiboard synchronization.

NI-IMAQ has both high-level I/O functions for maximum ease of use and low-level I/O functions for maximum flexibility and performance. Examples of high-level functions are snap and grab image acquisition. Examples of low-level functions are buffer setup and video configuration. NI-IMAQ enhances the performance of National Instruments IMAQ devices because it lets multiple devices operate at their peak performance.

NI-IMAQ includes a buffer and data manager that uses sophisticated techniques for handling and managing image acquisition buffers so that you can simultaneously acquire and process data. NI-IMAQ uses direct memory access (DMA) to transfer all data.

NI-IMAQ is a library of routines that work with National Instruments IMAQ devices. NI-IMAQ contains methods for overcoming difficulties ranging from simple device initialization to advanced high-speed real-time image acquisition. The number of services you need for your applications depends on the types of IMAQ devices you have and the complexity of your applications.

Application Development Environments

This release of NI-IMAQ supports the following Application Development Environments (ADEs) for Windows 95 and Windows NT.

- LabVIEW version 4.x
- LabWindows/CVI version 4.x
- Borland C/C++ version 4.5.x
- Microsoft Visual C/C++ version 2.x or 4.x



Although NI-IMAQ has been tested and found to work with these ADEs, other ADEs or higher versions of the ADEs listed above may also work.

Files on the NI-IMAQ software diskettes may be compressed. Always run the NI-IMAQ installation utility to extract the files you want. For a brief description of the directories produced by the install programs and the names and purposes of the uncompressed files, consult the readme.txt file.

Fundamentals of Building Windows Applications with NI-IMAQ

This chapter describes the fundamentals of creating NI-IMAQ applications for Windows 95 and Windows NT, describes the files used to build these applications, and tells you where to find sample programs.

The NI-IMAQ Libraries

The NI-IMAQ for Windows 95/NT function libraries are dynamic link libraries (DLLs), which means that NI-IMAQ routines are not linked into the executable files of applications. Only the information about the NI-IMAQ routines in the NI-IMAQ import libraries is stored in the executable files.

Import libraries contain information about their DLL-exported functions. They indicate the presence and location of the DLL routines. Depending on the development tools you are using, you may give the DLL routines information through import libraries or through function declarations.

Because using functional prototypes is a good programming practice, NI-IMAQ is packaged with functional prototype files for different Windows development tools.

Creating an Application

This section outlines the process for developing NI-IMAQ applications using C for Windows 95 and Windows NT. Detailed instructions on creating project and source files are not included. For information on creating and managing project files, consult the documentation included with your particular development environment.

When programming, use the following guidelines:

- You must define the constant _NIWIN prior to including any
 NI-IMAQ header files. You can define this constant in your source
 files by using the #define directive; that is, #define _NIWIN.
 Or, you can add the definition to your project file's preprocessor
 definitions if your environment supports this feature.
- All C source files that use NI-IMAQ functions must include the NIIMAQ. H header file. Add this file to the top of your source files.
- You must add the IMAQ.LIB import library to your project. Some environments allow you to add import libraries simply by inserting them into your list of project files. Other environments allow you to specify import libraries under the linker settings portion of the project file.
- When compiling, you will need to indicate where the compiler can find the NI-IMAQ header files and import libraries. Most of the files you need for development are located under the NI-IMAQ target installation directory. If you choose the default directory during installation, the target installation directory is C:\NIIMAQ. The include files are located under the include subdirectory. The import libraries are located under the lib\<environment> subdirectory for the following platforms:

 Development Environment
 Directory

 Microsoft Visual C++
 lib\msc

 Borland C++
 lib\bc

Table 2-1. Import Libraries

Sample Programs

Please refer to the readme.txt file located in the target installation directory for the latest details on NI-IMAQ sample programs. These programs are installed in the sample subdirectory under the target installation directory if you elected to install the sample files.

This chapter describes the classes of NI-IMAQ functions and briefly describes each function.

Introduction

NI-IMAQ functions are grouped according to the following classes:

- Generic functions
- High-level functions
 - Snap functions
 - Grab functions
 - Ring and sequence functions
 - Miscellaneous high-level functions
- Low-level functions
 - Interface functions
 - Session functions
 - Miscellaneous low-level functions

Generic Functions

Use generic functions in both high-level and low-level applications.

imgInterfaceOpen Opens by name an interface as specified

in the NI-IMAQ configuration utility,

IMAQconf

imgSessionOpen Opens a session and returns a session

ID

imgClose Closes a session or interface and

optionally unlocks and releases all buffers associated with the data type

High-Level Functions

Use high-level functions to quickly and easily capture images. If you need more advanced functionality, you can mix high-level functions with low-level functions.

Snap Functions

Snap functions program the session to capture all or a portion of a single frame or field to the user buffer.

imgSnap Performs a single frame and field

acquisition

imgSnapArea Performs an area-specific frame or field

acquisition

Grab Functions

Grab functions start a continuous image acquisition to a user buffer. Any frame or field can be copied from the grab buffer to another user buffer.

imgGrabSetup Configures and optionally starts a

continuous acquisition

imgGrab Performs a transfer from a continuous

acquisition session. Call this function only after calling imgGrabSetup.

imgGrabArea Performs a transfer from a continuous

acquisition. Call this function only after

calling imgGrabSetup.

Ring and Sequence Functions

Ring and sequence functions start and stop a continuous acquisition of multiple fields or frames.

imgRingSetup Prepares a session for acquiring

continuously and looping into buffer

list

imgSequenceSetup Prepares a session for acquiring a full

sequence into the buffer list

imgSessionStartAcquisitionStarts a session acquisition identified

by the session ID

imgSessionStopAcquisition Stops a session acquisition identified

by the session ID

Miscellaneous Functions

Miscellaneous functions set and get the acquisition window's region of interest and return information such as session status and buffer sizes.

imgSessionStatus Gets the current session status

imgSessionSetROI Sets the region of interest

imgSessionGetROI Gets the region of interest

imgSessionGetBufferSize Gets the minimum buffer size needed

for frame buffer allocation

Low-Level Functions

Use low-level functions when you require more direct hardware control.

Interface Functions

Interface functions load and control the selected IMAQ board and cameras. These functions use information stored by IMAQconf, the graphical IMAQ configuration utility.

imgInterfaceLock Locks a logical interface so that another

process cannot use it

imgInterfaceQueryNames Returns the names of the available

interfaces

imgInterfaceReset Performs a hardware reset on the

interface type and returns a status,

either good or bad

imgInterfaceUnlock Unlocks a logical interface, allowing

another process to use it

Session Functions

Use the session functions to directly control the image session, through which you set up any image acquisition, such as a sequence capture.

imgSessionAbort Stops an acquisition immediately

imgSessionAcquire Starts acquisition synchronously or

asynchronously to the frame buffers in

the associated session buffer list

imgSessionClearBuffer Clears a session's image data to the

specified pixel value

imgSessionClearTriggers Clears all session-associated triggers

imgSessionConfigure Specifies the buffer list to use with this

session

imgSessionCopyArea Copies an area of a session's buffer to a

user-specified buffer

imgSessionCopyBuffer Copies a session's image data to a user

buffer format

imgSessionExamineBuffer Extracts a buffer from a live acquisition;

lets you lock a buffer out of a continuous loop sequence for processing when you are performing a ring (continuous)

acquisition

imgSessionGetTriggerStatus

Returns a status on a specified trigger

line

imgSessionReleaseBuffer Releases a buffer that was previously

held with imgSessionExamineBuffer

imgSessionSaveBuffer Saves a buffer of a session to disk in

native operating-specific system format

such as bmp or PICT

imgSessionSetRTSImap Maps the internal RTSIbus triggers to

the external RTSIbus connector lines

imgSessionSetTrigger Causes a software trigger; simulates an

external trigger and can be called at

interrupt time

imgSessionWait Waits for an asynchronous acquisition

to complete

imgSessionWaitVblank Waits for the start of the next camera

vertical blank before returning

Miscellaneous Functions

You can use these functions to wait for host- or interface-specific events, change acquisition parameters, create buffers, and dispose of sessions and interfaces.

imgCameraAction Sends camera control information to a

camera (if applicable)

imgCreateBuffer Creates a user frame buffer based on the

geometric definitions of the associated

session

imgCreateBufList Creates a buffer list that is passed to

imgSessionConfigure

imgDisposeBuffer Disposes of a user frame buffer

imgDisposeBufList Purges all image buffers associated with

this buffer list and releases the buffer list

imgGetAttribute Returns an attribute for an interface or

session

imgGetBufferElement Gets an element of a specific type from

a buffer list

imgMemLock Locks all session-associated image

buffers in memory in preparation for an

acquisition

imgMemUnlock Unlocks all session-associated buffers

imgPlot Plots a buffer to a window given a native

window handle

imgSetAttribute Sets an attribute for an interface or

session

imgSetBufferElement Sets a buffer list element of a given type

to a specific value

imgShowError Returns a null terminated string

describing the error code

Programming with NI-IMAQ



This chapter contains an overview of the NI-IMAQ library, a description of the programming flow of NI-IMAQ, and programming examples. Flowcharts are included for the following operations: snap, grab, ring, sequence, and snap on external trigger, which mixes highlevel and low-level entry points.

Introduction

The NI-IMAQ API is divided into two groups, the high-level functions and the low-level functions. With the high-level functions, you can write programs quickly without having to learn the details of the low-level API and driver. The low-level functions give you finer granularity and control over your image acquisition process, but you must understand the API and driver in greater detail.

Note:

The high-level functions call low-level functions and use certain attributes that are listed in the high-level function description in the NI-IMAQ Function Reference Manual. Changing the value of these attributes while using low-level functions will affect the operation of the high-level functions.

High-Level Functions

The high-level function set supports four basic types of image acquisition:

- Snap acquires a single frame or field to a buffer
- *Grab* performs an acquisition that loops continually on one buffer; you obtain a copy of the acquisition buffer by *grabbing* a copy to a separate buffer that can be used for analysis
- Ring performs an acquisition that loops continually on a specified number of buffers
- Sequence performs an acquisition that acquires a specified number of buffers, then stops

Low-Level Functions

The low-level function set supports all types of acquisition and can be used to:

- Create a custom acquisition sequence or ring
- Create and manage your own buffers
- Set session and interface attributes to adjust image quality and size
- Start a synchronous or asynchronous acquisition
- Extract buffers out of a live acquisition for analysis
- Set up and control triggered acquisitions

Establishing Interface Connections and Sessions

To acquire images using the high-level or low-level functions, you must first learn how to establish a connection to an interface and create a session. See the *Interface Functions* and *Session Functions* sections in this chapter for information on how to manage interfaces and sessions, then refer to the high-level or low-level samples for information on acquiring images.

Interface Functions

Use interface functions to query the number of available interfaces, establish a connection to, control access to, and initialize hardware such as the IMAQ-1408. All interfaces in NI-IMAQ are specified by a name. By default, the system creates default names for the number of boards in your system. These names observe the convention shown in Table 4-1.

Interface Name	Board Installed
img0	Board 0
img1	Board 1
img <i>n</i>	Board n

Table 4-1. Interface Naming Convention

You can edit existing or create new interfaces by using the IMAQconf configuration utility. You also can use IMAQconf to configure the board serial number and the default state of a particular interface.

Before you can acquire image data successfully, you must open an interface by using the imgInterfaceOpen function.

imgInterfaceOpen requires an interface name and returns a handle to this interface. NI-IMAQ then uses this handle to reference this interface when using other NI-IMAQ functions.

To establish a connection to the first board in your system, use the following program example:

```
INTERFACE_ID interfaceID;
if (imgInterfaceOpen("img0", &interfaceID) == IMG_ERR_GOOD)
{
    ... user code ...
    imgClose(interfaceID, FALSE);
}
```

This example opens an interface to img0. When the program is finished with the interface, it closes the interface using the imgClose function.

For a complete list of the available interface functions, refer to the *NI-IMAO Function Reference Manual*.

Session Functions

Use session functions to configure the type of acquisition you want to perform on a particular interface. After you have established a connection to an interface, you need to create a session and configure it to perform the type of acquisition you require.

To create a session, call the imgSessionOpen function. This function requires a valid interface handle and returns a handle to a session. NI-IMAQ then uses this session handle to reference this session when using other NI-IMAQ calls.

To create a session, use the following example program:

```
INTERFACE_ID interfaceID;
SESSION_ID sessionID;
if (imgInterfaceOpen("img0", &interfaceID) == IMG_ERR_GOOD)
{
   if (imgSessionOpen(interfaceID, &sessionID) == IMG_ERR_GOOD)
   {
      ... user code ...
      imgClose(sessionID, FALSE);
   }
   imgClose(interfaceID, FALSE);
}
```

This example opens an interface to img0 and then creates a session to acquire images. When the program is finished with the interface and session, it then closes both handles using the imgClose function.

For a complete list of the available session functions, refer to the *NI-IMAQ Function Reference Manual*.

Managing Buffers

Buffer management can be performed either by you or automatically by NI-IMAQ. If the high-level acquisition routines (imgSnap, imgGrab, imgSequenceSetup, and imgRingSetup) are initiated with NULL pointers for buffer addresses, NI-IMAQ will automatically allocate a buffer and return the value of the buffer pointer to you. After you have a buffer pointer, you can use this pointer in successive calls.

For greater control of the acquisition buffers, such as creating buffers larger than the image size for adding borders, you can create them by calling a memory allocation routine (for example, malloc) or using the low-level function imgCreateBuffer. When creating buffers using either approach, dispose of the buffers using free or imgDisposeBuffer when applicable to free PC memory for maximum performance.

Introductory Programming Examples

This section introduces some examples for performing the different types of image acquisition and includes both high-level and low-level function examples. The error codes that NI-IMAQ returns are not included in the examples. In your programs, always check the return code for errors.

High-Level Snap Functions

A *snap* acquires a single image into a memory buffer. Snap functions include imgSnap and imgSnapArea. Use these functions to acquire a single frame or field to a buffer. To use these functions, you must have a valid session handle.

When you invoke a snap, it initializes the board and acquires the next incoming video frame (or field) to a buffer. A snap is appropriate for low-speed or single-capture applications where ease of programming is essential. Figure 4-1 illustrates a typical snap programming order.

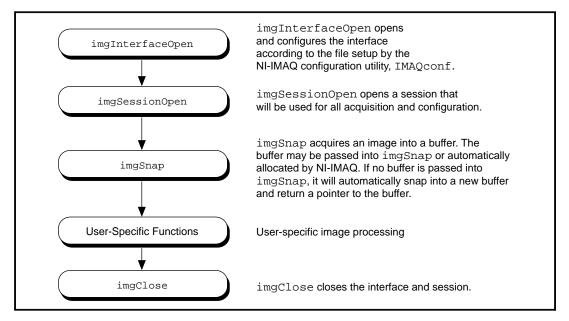


Figure 4-1. Snap Programming Flowchart

```
int main(void)
 INTERFACE_ID interfaceID;
 SESSION_ID sessionID;
 Int8*
             buffer = NULL;
 IMG_ERR
             error;
 uInt32
              top, left, height, width, rowBytes;
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // pass a pointer to a NULL pointer and the driver will allocate
 // a buffer of the appropriate size for you.
 error = imgSnap(sessionID, &buffer);
 // get the image dimensions. These default dimensions depend on the type
 // of camera that is currently configured.
 error = imgSessionGetROI(sessionID, &top, &left, &height, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ROWBYTES, &rowBytes);
 // process the image
 my_process_function(buffer, top, left, height, width, rowBytes);
 // close this interface and free all resources associated with it,
 // such as the buffer that was allocated by the driver during imgSnap
 imgClose(interfaceID, TRUE);
 return(0);
```

Example 1 opens an interface and a session and then performs a single snap. The buffer pointer that is passed to imgSnap is initialized to NULL, which instructs imgSnap to automatically allocate a buffer for the image. The size of the buffer is calculated based on the region of interest (ROI) and the rowByte attributes: ROI height multiplied by rowByte. When you open a session, the ROI values are initialized from the acquisition window (ACQWINDOW) dimensions that are configured in IMAQconf. The ACQWINDOW dimensions will vary depending on the type of camera you are using.

The sample then calls a process function to analyze the image. When the program is finished, it calls imgClose with the interface handle and sets the **freeResources** flag to TRUE. This instructs NI-IMAQ to free all of the resources associated with this interface, which releases the session as well as the memory buffer allocated by imgSnap.

High-Level Grab Functions

A *grab* is a continuous high-speed acquisition of data to a single buffer in host memory. Grab functions include imgGrabSetup, imgGrab and imgGrabArea. You can use these functions to perform an acquisition that loops continually on one buffer. A copy of the acquisition buffer is obtained by grabbing a copy to a separate buffer. To use these functions, you must have a valid session handle.

Calling imgGrabSetup initializes a session for a grab acquisition. After imgGrabSetup, each successive grab will copy the last acquired buffer into a user buffer where you can perform processing on the image. A grab is appropriate for high-speed applications where you need processing performed on only one image at a time. Figure 4-2 illustrates a typical grab programming order.

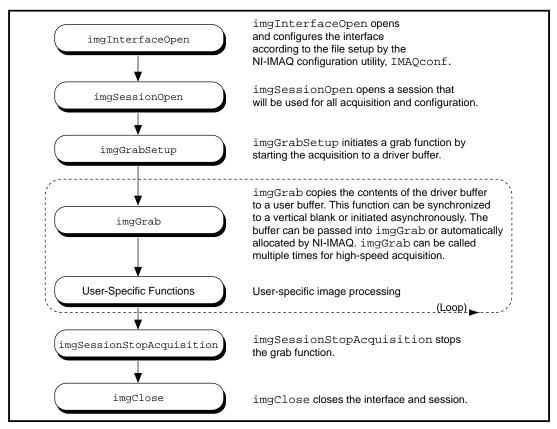


Figure 4-2. Grab Programming Flowchart

Example 2 demonstrates how to perform a grab using imgGrabArea.

```
int main(void)
{
   INTERFACE_ID interfaceID;
   SESSION_ID sessionID;
   Int8* buffer;
   IMG_ERR error;
   uInt32 top, left, height, width, rowBytes, bytesPerPixel;

// open an interface and a session
   error = imgInterfaceOpen("img0", &interfaceID);
   error = imgSessionOpen(interfaceID, &sessionID);
```

```
// configure the session for a grab but do not start the acquisition yet
 error = imgGrabSetup(sessionID, FALSE);
 // get the image dimensions
 error = imgSessionGetROI(sessionID, &top, &left, &height, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ROWBYTES, &rowBytes);
 error = imgGetAttribute(sessionID, IMG_ATTR_BYTESPERPIXEL, &bytesPerPixel);
 // calculate a new grab area dimension
 height = height >> 1;
 width = width >> 1;
 rowBytes = width * bytesPerPixel;
 // start the acquisition
 error = imgSessionStartAcquisition(sessionID);
 // allocate our own buffer for storing a copy
 buffer = (Int8*) malloc(rowBytes * height);
 // grab until some condition is met
 while(1)
  // grab a copy of the acquisition buffer into my own user buffer for analysis
  error = imgGrabArea(sessionID, &buffer, TRUE, top, left, height, width, rowBytes);
  // process the image, if some condition is met, then terminate
  if (my_process_function(buffer, top, left, height, width, rowBytes))
    break;
   ... calculate new dimensions and reallocate buffer if necessary ...
 // stop the grab acquisition
 error = imgSessionStopAcquisition(sessionID);
 // free our user buffer
 free(buffer);
 // close this interface, free all resources
 imgClose(interfaceID, TRUE);
 return(0);
}
```

Example 2 performs multiple grabs until an appropriate condition is met. The program configures the session to perform a grab operation by calling the imgGrabSetup function. The program then calculates the area to grab using the current ROI, rowBytes, and BYTESPERPIXEL, and the acquisition is started by calling

imgSessionStartAcquisition. In this example, we allocate our own user buffer for grabbing and pass this buffer to imgGrabArea. When the acquisition is complete, it stops. The program then frees the user buffer and all of the resources associated with this interface by calling imgClose.

High-Level Ring and Sequence Functions

Ring and sequence functions include imgRingSetup, imgSequenceSetup, imgSessionStartAcquisition and imgStopAcquisition. Use these functions to perform a continuous acquisition that loops or stops after a certain number of images have been captured.

A ring initiates a continuous high-speed acquisition to multiple buffers. Calling imgRingSetup initiates a ring. imgRingSetup specifies both the buffer list that will be used for transfers and the number of buffers. After imgRingSetup is called, you can monitor the status of the transfer and perform processing on any of the buffers in the ring. A ring is appropriate for high-speed applications where you need to perform processing on every image. You must use multiple buffers because processing times may vary depending on other applications and processing results. You can configure a ring to acquire every frame or to skip a fixed number of frames between each acquisition.

For certain applications, you can temporarily extract a buffer from the ring to prevent it from being overwritten during the ring's next pass. Use the imgSessionExamineBuffer and imgSessionReleaseBuffer functions to do this. Figure 4-3 illustrates a typical ring programming order.

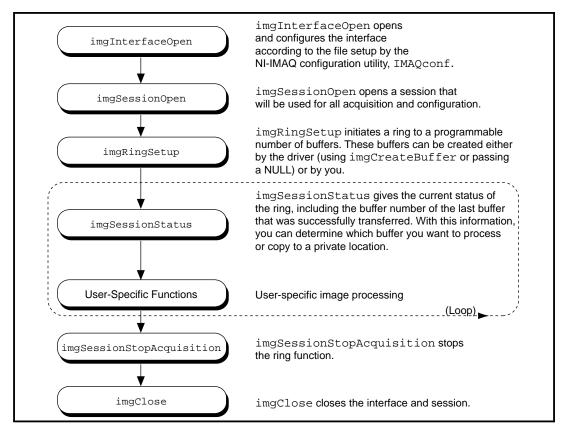


Figure 4-3. Ring Programming Flowchart

A *sequence* initiates a variable-length and variable-delay transfer to multiple buffers. You can configure the delay between acquisitions with SequenceSetup and specify both the buffer list that will be used for transfers and the number of buffers. After imgSequenceSetup, you can monitor the status of the transfer and perform processing on any of the buffers in the sequence or you can wait until the acquisition completes and process all buffers simultaneously.

A sequence is appropriate for applications where you need to perform processing on multiple images. You can configure a sequence to acquire every frame or skip a variable number of frames between each image. Figure 4-4 illustrates a typical sequence programming order.

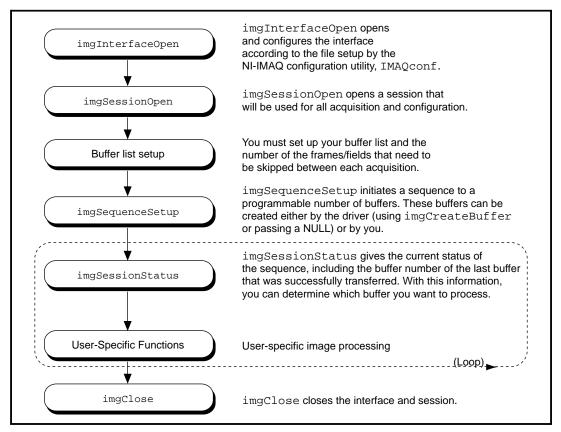


Figure 4-4. Sequence Programming Flowchart

Example 3 demonstrates how to perform a ring acquisition using imgRingSetup.

```
int main(void)
{
    INTERFACE_ID interfaceID;
    SESSION_ID sessionID;
    uInt32 top, left, height, width, rowBytes;
    Int32 error = 0;
    uInt32 status, lastBufNum, currBufNum;
    Int8* buffers[6];
```

```
// open an interface and a session
error = imgInterfaceOpen("img0", &interfaceID);
error = imgSessionOpen(interfaceID, &sessionID);
// initialize buffer pointers to NULL
memset(buffers, 0x00, sizeof(buffers));
// configure the session for a ring with six buffers; have the driver allocate the
// buffers
// only acquire every third video frame and do not start the acquisition yet
error = imgRingSetup(sessionID, 6, (void**)buffers, 3, FALSE);
// get the image dimensions
error = imgSessionGetROI(sessionID, &top, &left, &height, &width);
error = imgGetAttribute(sessionID, IMG_ATTR_ROWBYTES, &rowBytes);
// start the acquisition
error = imgSessionStartAcquisition(sessionID);
// run until some condition is met
lastBufNum = currBufNum = 0xFFFFFFF;
while(1)
 // spin waiting for the most current buffer
 // until the first image is acquired, imgSessionStatus will return 0xFFFFFFF for
 // the current buffer number
 while(lastBufNum == currBufNum)
   imgSessionStatus(sessionID, &status, &currBufNum);
 // the buffer number returned will be in the range from 0 to 5
 lastBufNum = currBufNum;
 // process the image, if some condition then terminate
 if (my_process_function(buffers[currBufNum], top, left, height, width, rowBytes))
   break;
}
// stop the ring acquisition
imgSessionStopAcquisition(sessionID);
// close this interface, free all resources
imgClose(interfaceID, TRUE);
return(0);
```

Example 3 sets up a ring containing six buffers and sets the skip count to three, which causes the program to acquire on every third frame. A *skip count* is the number of frames skipped prior to acquiring an image to a buffer. The program then loops, waiting for the next buffer to be acquired. The imgSessionStatus function queries NI-IMAQ for the buffer number of the last valid buffer that has been acquired. The last valid buffer is defined as the buffer that contains the most recent video image. This process will continue until a designated condition is met and then the acquisition stops.

Example 4 demonstrates how to perform a sequence acquisition using imgSequenceSetup.

```
int main(void)
 INTERFACE_ID interfaceID;
 SESSION_ID
              sessionID;
               i, top, left, height, width, rowBytes, bytesPerPixel;
 uInt32
 Int32
              error = 0;
 Int8*
              buffers[10];
 uInt32
              skips[10];
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // get the image dimensions
 error = imgSessionGetROI(sessionID, &top, &left, &height, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ROWBYTES, &rowBytes);
 error = imgGetAttribute(sessionID, IMG_ATTR_BYTESPERPIXEL, &bytesPerPixel);
 // calculate a new ROI
 height = height >> 1;
 width = width >> 1;
 rowBytes = width * bytesPerPixel;
 top += 10;
 left += 10;
 // now reset the ROI and the rowBytes
 // these attributes are used by imgSequenceSetup
 imgSessionSetROI(sessionID, top, left, height, width);
 imgSetAttribute(sessionID, IMG_ATTR_ROWBYTES, rowBytes);
```

```
// initialize buffer pointers and skip count arrays
// we will give a skip count equal to i, skip 1 frame, 2 frames, 3 frames, and so on
for (i = 0; i < 10; i++)
 buffers[i] = (Int8*) malloc(rowBytes * height);
 skips[i] = i;
}
// configure the session for a sequence with 10 buffers using buffers that we have
// allocated
// start the acquisition now and signal that the call is synchronous
error = imgSequenceSetup(sessionID, 10, (void**)buffers, skips, TRUE, FALSE);
// now call our analysis function for each buffer
for (i = 0; i < 10; i++)
 my_process_function(buffers[i], top, left, height, width, rowBytes);
// free our buffers
for (i = 0; i < 10; i++)
 free(buffers[i]);
// close this interface, free all resources
imgClose(interfaceID, TRUE);
return(0);
```

Example 4 sets up a sequence that uses 10 user-allocated buffers. Unlike the ring example, each buffer in the sequence has its own skip count associated with it. The skip count is the number of frames to skip prior to acquiring the next image. The acquisition is started at setup time and the setup call is synchronous.

Performing a Snap Using Low-Level Functions

Example 5 demonstrates how to perform a snap acquisition using low-level calls.

```
int main(void)
 uInt32
             width, height;
             bufSize;
 uInt32
 INTERFACE_ID interfaceID = 0;
 SESSION ID sessionID = 0;
 BUFLIST_ID buflistID = 0;
             buffer = NULL;
 Int8*
 Int32
             error = 0;
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // create a buffer list with one element
 error = imgCreateBufList(1, &buflistID);
 // these attributes default to the maximum width and height for the
 // default camera
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_HEIGHT, &height);
 // make the width longword aligned
 width = ((width + 3) & 0xFFFFFFC);
 // set acquisition window width and rowBytes to the value */
 error = imgSetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, width);
 error = imgSetAttribute(sessionID, IMG_ATTR_ROWBYTES, width);
 // set the ROI width to the same
 error = imgSetAttribute(sessionID, IMG_ATTR_ROI_WIDTH, width);
 // calculate buffer size needed for acquisition buffer
 bufSize = width * height;
 // create a buffer and configure the buffer list
 error = imgCreateBuffer(sessionID, FALSE, bufSize, &buffer);
 // the next three calls assigns the following to buffer list element 0:
 // 1) buffer pointer that will contain image
    2) size of the buffer for buffer element 0
 //
    3) command to stop acquisition when this element is reached
 error = imgSetBufferElement(buflistID, 0, IMG_BUFF_ADDRESS, (uInt32)buffer);
 error = imgSetBufferElement(buflistID, 0, IMG_BUFF_SIZE, bufSize);
 error = imgSetBufferElement(buflistID, 0, IMG_BUFF_COMMAND, IMG_CMD_STOP);
```

```
// lock down the buffers contained in the buffer list
 error = imgMemLock(buflistID);
 // configure the session to use this buffer list */
 error = imgSessionConfigure(sessionID, buflistID);
 // start the acquisition, synchronous, no callback function
 error = imgSessionAcquire(sessionID, FALSE, NULL);
 // process the image
 my_process_function(buffer, ...);
 // unlock the buffers in the buffer list
 imgMemUnlock(buflistID);
 // dispose of the buffer
 imgDisposeBuffer(buffer);
 // close this buffer list
 imgDisposeBufList(buflistID, FALSE);
 // close session
 imgClose(sessionID, FALSE);
 // close interface
 imgClose(interfaceID, FALSE);
 return(0);
}
```

Example 5 sets up a single-frame acquisition to a buffer allocated by NI-IMAQ. The program retrieves the acquisition window width of the selected camera and aligns it on a 32-bit boundary. You must align both the acquisition window width and rowBytes on a 32-bit boundary to ensure that your image is acquired properly. The software does not perform this alignment for you unless you select a scaling option. Although IMAQCONF performs this alignment for you when you acquire an image with it, you must perform the alignment yourself if you use window widths not aligned on a 32-bit boundary.

After the program sets the ROI, it locks the memory and acquires the image. If you choose to plot the image using the imagplot function, you must align the image width on a 32-bit boundary as well.

Performing a Grab Using Low-Level Functions

Example 6 demonstrates how to perform a grab acquisition using lowlevel calls.

```
int main(void)
 uInt32
             width, height;
             bufSize, bufNum;
 uInt32
 INTERFACE_ID interfaceID = 0;
 SESSION_ID sessionID = 0;
 BUFLIST_ID buflistID = 0;
              buffer = NULL;
 Int8*
             copyBuffer = NULL;
 uInt8*
 Int32
              error = 0;
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // create a buffer list with one element
 error = imgCreateBufList(1, &buflistID);
 // these attributes default to the maximum width and height for the
 // default camera
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_HEIGHT, &height);
 // make the width longword aligned.
 width = ((width + 3) & 0xFFFFFFC);
 // set acquisition window width and rowBytes to the value
 error = imgSetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, width);
 error = imgSetAttribute(sessionID, IMG_ATTR_ROWBYTES, width);
 // set the ROI width to the same
 error = imgSetAttribute(sessionID, IMG_ATTR_ROI_WIDTH, width);
 // calculate buffer size needed for acquisition buffer
 bufSize = width * height;
 // allocate our own buffer for storing copy
 copyBuffer = malloc(bufSize);
 // create a buffer and configure the buffer list
 error = imgCreateBuffer(sessionID, FALSE, bufSize, &buffer);
```

```
// the next three calls assigns the following to buffer list element 0:
      1) buffer pointer that will contain image
      2) size of the buffer for buffer element 0
      3) command to stop acquisition when this element is reached
error = imgSetBufferElement(buflistID, 0, IMG_BUFF_ADDRESS, (uInt32)buffer);
error = imgSetBufferElement(buflistID, 0, IMG_BUFF_SIZE, bufSize);
error = imgSetBufferElement(buflistID, 0, IMG_BUFF_COMMAND, IMG_CMD_LOOP);
// lock down the buffers contained in the buffer list
error = imgMemLock(buflistID);
// configure the session to use this buffer list
error = imgSessionConfigure(sessionID, buflistID);
// start the acquisition, asynchronous
error = imgSessionAcquire(sessionID, TRUE, NULL);
// grab until some condition is met
while(1)
 // save a copy to copyBuffer, wait for VBLANK period
 error = imgSessionCopyBuffer(sessionID, 0, copyBuffer, TRUE);
 // process the image, if some condition is met, then terminate
 if (my_process_function(copyBuffer, ...))
  break;
}
// stop the acquisition
imgSessionAbort(sessionID, &bufNum);
// unlock the buffers in the buffer list
imgMemUnlock(buflistID);
// dispose of the buffer
imgDisposeBuffer(buffer);
// close this buffer list
imgDisposeBufList(buflistID, FALSE);
```

```
// close this session
imgClose(sessionID, FALSE);

// close interface handle
imgClose(interfaceID, FALSE);

// free our copy buffer
free(copyBuffer);

return(0);
}
```

Example 6 sets up a continuous acquisition to a single user-allocated buffer. As described in Example 5, the program retrieves the acquisition window width of the selected camera and aligns it on a 32-bit boundary. The program creates a buffer list to describe the acquisition buffers. Next, the program sets the ROI to the acquisition window width. The program performs a calculation to determine the correct memory requirements of the user buffer. The program creates the buffer and configures buffer element 0 for a single continuous acquisition. the program then locks the memory and starts the image acquisition asynchronously. The main processing loop of the code shows how to wait for vertical blank and copy the buffer to an analysis buffer.

Keep your analysis code fast to minimize the number of missed frames during analysis. If you need more time to examine a buffer, set up a multiple-buffer ring and call imgSessionExamineBuffer to extract the desired buffer from the live sequence.

Performing a Ring Acquisition Using Low-Level Functions

Example 7 demonstrates how to perform a ring acquisition using low-level calls.

```
int main(void)
 uInt32
              top, left, width, height, rowBytes, i;
 uInt32
              bufSize;
 INTERFACE_ID interfaceID = 0;
 SESSION_ID sessionID = 0;
 BUFLIST_ID buflistID = 0;
              lastBufNum, currBufNum, bufCmd, bufNum;
 uInt32
 Int8*
              buffers[6];
              error = 0;
 Int32
 // initialize buffer pointers to NULL
 memset(buffers, 0x00, sizeof(buffers));
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // create a buffer list with 6 elements
 error = imgCreateBufList(6, &buflistID);
 // these attributes default to the maximum width and height for the
 // default camera
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_HEIGHT, &height);
 // make the width longword aligned
 width = ((width + 3) & 0xFFFFFFC);
 // set acquisition window width and rowBytes to the value
 error = imgSetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, width);
 error = imgSetAttribute(sessionID, IMG_ATTR_ROWBYTES, width);
 // set the ROI width to the same
 error = imgSetAttribute(sessionID, IMG_ATTR_ROI_WIDTH, width);
 // calculate buffer size needed for acquisition buffer
 bufSize = width * height;
```

```
// the next set of functions assign the following to the buffer list elements:
      1) buffer pointer that will contain image
//
      2) size of the buffer for each buffer element
      3) command to go to next buffer or loop when the last element is reached
for (i = 0; i < 6; i++)
error = imgCreateBuffer(sessionID, FALSE, bufSize, &buffers[i]);
error = imgSetBufferElement(buflistID, i, IMG_BUFF_ADDRESS, (uInt32)buffers[i]);
error = imgSetBufferElement(buflistID, i, IMG_BUFF_SIZE, bufSize);
bufCmd = (i == 5) ? IMG_CMD_LOOP : IMG_CMD_NEXT;
error = imgSetBufferElement(buflistID, i, IMG_BUFF_COMMAND, bufCmd);
// lock down the buffers contained in the buffer list
error = imgMemLock(buflistID);
// configure the session to use this buffer list
error = imgSessionConfigure(sessionID, buflistID);
// start the acquisition, asynchronous
error = imgSessionAcquire(sessionID, TRUE, NULL);
// run until user wants to stop */
lastBufNum = currBufNum = 0xFFFFFFF;
while(1)
 // spin waiting for the most current buffer
 // until the first image is acquired, imgSessionStatus will return 0xFFFFFFFF for
 // the current buffer number
 while (lastBufNum == currBufNum)
   imgGetAttribute(sessionID, IMG_ATTR_LAST_VALID_BUFFER, &currBufNum);
 lastBufNum = currBufNum;
 // process the image, if some condition then terminate
 if (my_process_function(buffers[currBufNum], top, left, height, width, rowBytes))
   break;
// stop the acquisition
error = imgSessionAbort(sessionID, &bufNum);
```

```
// unlock the buffers in the buffer list
error = imgMemUnlock(buflistID);

// dispose of the buffers
for (i = 0; i < 6; i++)
imgDisposeBuffer(buffers[i]);

// close this buffer list
error = imgDisposeBufList(buflistID, FALSE);

// close this session
error = imgClose(sessionID, FALSE);

// close interface handle
error = imgClose(interfaceID, FALSE);

return(0);
}</pre>
```

Example 7 sets up a continuous acquisition to multiple buffers allocated by NI-IMAQ. As described in Example 5, the program retrieves the acquisition window width of the selected camera and aligns it on a 32-bit boundary. It then creates a buffer list to describe the acquisition buffers. Next, the program sets the ROI to the acquisition window width. The program calculates the correct memory requirements of the frame buffer. However, this is not necessary if you choose to use the default acquisition window width, rowBytes, and ROI. In this case, NI-IMAQ will allocate the correct size buffer if you pass a NULL as the size parameter to imgCreateBuffer. The buffer is created and the buffer list is configured for each buffer element in the ring. The memory is locked and the image acquisition is started asynchronously.

IMG_ATTR_LAST_VALID_BUFFER until it changes. If your buffer analysis requires many computations, call

imgSessionExamineBuffer to extract the desired buffer from the live sequence. When using imgSessionExamineBuffer, the buffer requested is literally pulled from the looping sequence for the duration of the analysis. Use imgSessionReleaseBuffer to return the buffer to the continuous sequence.

Performing a Sequence Acquisition Using Low-Level Functions

Example 8 demonstrates how to perform a sequence acquisition using low-level calls.

```
int main(void)
 uInt32
             width, height, i;
 uInt32
              bufSize;
 INTERFACE_ID interfaceID = 0;
 SESSION_ID sessionID = 0;
 BUFLIST ID buflistID = 0;
             error = 0;
 Int32
 uInt32
             bufCmd;
 Int8*
             buffers[10];
 uInt32
             skips[10];
 // initialize buffer pointers and skip count arrays
 for (i = 0; i < 10; i++)
  buffers[i] = NULL;
  skips[i] = i;
 // open an interface and a session
 error = imgInterfaceOpen("img0", &interfaceID);
 error = imgSessionOpen(interfaceID, &sessionID);
 // create a buffer list with n elements */
 error = imgCreateBufList(NUM_SEQ_BUFFERS, &buflistID);
 // these attributes default to the maximum width and height for the
 // default camera
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, &width);
 error = imgGetAttribute(sessionID, IMG_ATTR_ACQWINDOW_HEIGHT, &height);
 // make the width longword aligned
 width = ((width + 3) & 0xFFFFFFC);
 // set acquisition window width and rowBytes to the value
 error = imgSetAttribute(sessionID, IMG_ATTR_ACQWINDOW_WIDTH, width);
 error = imgSetAttribute(sessionID, IMG_ATTR_ROWBYTES, width);
```

```
// set the ROI width to the same
error = imgSetAttribute(sessionID, IMG_ATTR_ROI_WIDTH, width);
// calculate buffer size needed for acquisition buffer
bufSize = width * height;
// the next set of functions assign the following to the buffer list elements:
     1) buffer pointer that will contain image
      2) size of the buffer for each buffer element
      3) command to go to next buffer or loop when the last element is reached
for (i = 0; i < 10; i++)
 error = imgCreateBuffer(sessionID, FALSE, bufSize, &buffers[i]);
 error = imgSetBufferElement(buflistID, i, IMG_BUFF_ADDRESS,(uInt32)buffers[i]);
 error = imgSetBufferElement(buflistID, i, IMG_BUFF_SIZE, bufSize);
 bufCmd = (i == 9) ? IMG_CMD_STOP : IMG_CMD_NEXT;
 error = imgSetBufferElement(buflistID, i, IMG_BUFF_COMMAND, bufCmd);
}
// lock down the buffers contained in the buffer list
error = imgMemLock(buflistID);
// configure the session to use this buffer list
error = imgSessionConfigure(sessionID, buflistID);
// start the acquisition, synchronous
error = imgSessionAcquire(sessionID, FALSE, NULL);
// now call our analyses function for each buffer
for (i = 0; i < 10; i++)
 my_process_function(buffers[i], ...);
// unlock the buffers in the buffer list
error = imgMemUnlock(buflistID);
// dispose of the buffers
for (i = 0; i < 10; i++)
 imgDisposeBuffer(buffers[i]);
// close this buffer list
error = imgDisposeBufList(buflistID, FALSE);
// close this session
error = imgClose(sessionID, FALSE);
```

```
// close interface handle
error = imgClose(interfaceID, FALSE);
return(0);
```

Example 8 sets up a sequence acquisition to multiple buffers allocated by NI-IMAQ. As described in Example 5, the program retrieves the acquisition window width of the selected camera and aligns it on a 32-bit boundary. It creates a buffer list to describe the acquisition buffers. Next, the program sets the ROI to the acquisition window width. The program calculates the correct memory requirements of the frame buffer. However, this is not necessary if you choose to use the default acquisition window width, rowBytes, and ROI. In this case, NI-IMAQ will allocate the correct size buffer if you pass a NULL as the size parameter to imgCreateBuffer. The program creates the buffer and configures the buffer list for each buffer element in the ring. The program locks the memory and starts the image acquisition asynchronously.

The main processing loop of the code shows how to process each buffer acquired in sequential order.

Snap on Trigger Programming

Snap acquires a single image into a memory buffer. As shown in Figure 4-5, the program will not initiate the snap until a rising edge of external trigger 0 occurs.

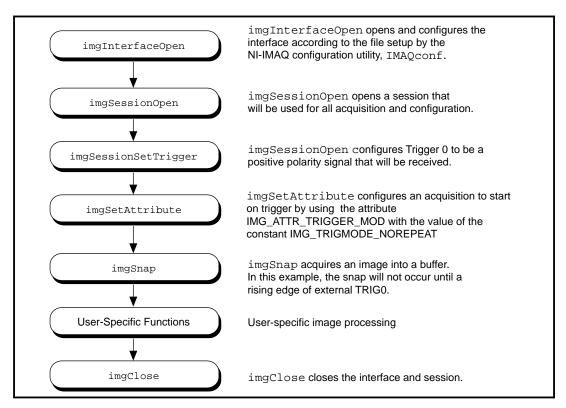
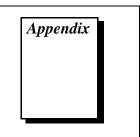


Figure 4-5. Snap on Trigger Programming Flowchart





For your convenience, this appendix contains forms to help you gather the information necessary to help us solve your technical problems and a form you can use to comment on the product documentation. When you contact us, we need the information on the Technical Support Form and the configuration form, if your manual contains one, about your system configuration to answer your questions as quickly as possible.

National Instruments has technical assistance through electronic, fax, and telephone systems to quickly provide the information you need. Our electronic services include a bulletin board service, an FTP site, a FaxBack system, and e-mail support. If you have a hardware or software problem, first try the electronic support systems. If the information available on these systems does not answer your questions, we offer fax and telephone support through our technical support centers, which are staffed by applications engineers.

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United States: (512) 794-5422 or (800) 327-3077 Up to 14,400 baud, 8 data bits, 1 stop bit, no parity

United Kingdom: 01635 551422

Up to 9,600 baud, 8 data bits, 1 stop bit, no parity

France: 01 48 65 15 59

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FTP Support

To access our FTP site, log on to our Internet host, ftp.natinst.com, as anonymous and use your Internet address, such as joesmith@anywhere.com, as your password. The support files and documents are located in the /support directories.



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You can submit technical support questions to the applications engineering team through e-mail at the Internet address listed below. Remember to include your name, address, and phone number so we can contact you with solutions and suggestions.

support@natinst.com

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	Telephone	Fax
Australia	03 9879 5166	03 9879 6277
Austria	0662 45 79 90 0	0662 45 79 90 19
Belgium	02 757 00 20	02 757 03 11
Canada (Ontario)	905 785 0085	905 785 0086
Canada (Quebec)	514 694 8521	514 694 4399
Denmark	45 76 26 00	45 76 26 02
Finland	09 527 2321	09 502 2930
France	01 48 14 24 24	01 48 14 24 14
Germany	089 741 31 30	089 714 60 35
Hong Kong	2645 3186	2686 8505
Israel	03 5734815	03 5734816
Italy	02 413091	02 41309215
Japan	03 5472 2970	03 5472 2977
Korea	02 596 7456	02 596 7455
Mexico	5 520 2635	5 520 3282
Netherlands	0348 433466	0348 430673
Norway	32 84 84 00	32 84 86 00
Singapore	2265886	2265887
Spain	91 640 0085	91 640 0533
Sweden	08 730 49 70	08 730 43 70
Switzerland	056 200 51 51	056 200 51 55
Taiwan	02 377 1200	02 737 4644
U.K.	01635 523545	01635 523154

Technical Support Form

Photocopy this form and update it each time you make changes to your software or hardware, and use the completed copy of this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

If you are using any National Instruments hardware or software products related to this problem, include the configuration forms from their user manuals. Include additional pages if necessary.

Name	
Company	
Address	
Fax ()Phone ()	
Computer brand Model	Processor
Operating system (include version number)	
Clock speedMHz RAMMB	Display adapter
Mouseyesno Other adapters installe	ed
Hard disk capacityMB Brand	
Instruments used	
National Instruments hardware product model	Revision
Configuration	
•	Version
Configuration	
The problem is:	
1	
List any error messages:	
The following steps reproduce the problem:	

NI-IMAQ Hardware and Software Configuration Form

Record the settings and revisions of your hardware and software on the line to the right of each item. Complete a new copy of this form each time you revise your software or hardware configuration, and use this form as a reference for your current configuration. Completing this form accurately before contacting National Instruments for technical support helps our applications engineers answer your questions more efficiently.

National Instruments Products

IMAQ hardware
Interrupt level of hardware
DMA channels of hardware
Base I/O address of hardware
Programming choice
NI-IMAQ, IMAQ Vision, LabVIEW, or LabWindows version
Other boards in system
Base I/O address of other boards
DMA channels of other boards
Interrupt level of other boards
Other Products
Computer make and model
Microprocessor
Clock frequency or speed
PCI chipset
Type of video board installed
Operating system version
Operating system mode
Programming language
Programming language version
Other boards in system
Base I/O address of other boards
DMA channels of other boards
Interrupt level of other boards

Documentation Comment Form

NI-IMAQ User Manual

Edition Date: November 1996

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Prefix	Meaning	Value
p-	pico-	10-12
n-	nano-	10-9
μ-	micro-	10 ⁻⁶
m-	milli-	10-3
k-	kilo-	10^{3}
M-	mega-	10^{6}
G-	giga-	109

Numbers/Symbols

% percent

+ positive of, or plus

+5V 5 V signal

negative of, or minus

per

± plus or minus

 Ω ohm

A

A amperes

AC alternating current

acquisition window the image size specific to a video standard or camera resolution

active line region the region of lines actively being stored; defined by a line start

(relative to VSYNC) and a line count

active pixel region the region of pixels actively being stored; defined by a pixel start

(relative to HSYNC) and a pixel count

A/D analog-to-digital

ADC analog-to-digital converter—an electronic device, often an

integrated circuit, that converts an analog voltage to a digital

number

address character code that identifies a specific location (or series of

locations) in memory

ANSI American National Standards Institute

antichrominance filter removes the color information from the video signal

API application programming interface

AQ DONE signals that the acquisition of a frame or field is completed

AQ_IN_PROGRESS signals that the acquisition of video data is in progress

area a rectangular portion of an acquisition window or frame that is

controlled and defined by software

array ordered, indexed set of data elements of the same type

ASIC Application-Specific Integrated Circuit—a proprietary

semiconductor component designed and manufactured to perform

a set of specific functions for a specific customer

aspect ratio the ratio of a signal's width to its height

В

b bit—one binary digit, either 0 or 1

B byte—eight related bits of data, an eight-bit binary number; also

used to denote the amount of memory required to store one byte

of data

back porch the area of the video signal between the rising edge of the

horizontal sync signal and the active video information

black reference level the level that represents the darkest an image can get

See also white reference level.

buffer temporary storage for acquired data

bus the group of conductors that interconnect individual circuitry in a

computer, such as the PCI bus; typically the expansion vehicle to

which I/O or other devices are connected

C

C Celsius

cache high-speed processor memory that buffers commonly used

instructions or data to increase processing throughput

CCIR Comite Consultatif International des Radiocommunications—a

committee that developed standards for color video signals

chrominance the color information in a video signal

CMOS complementary metal-oxide semiconductor

compiler a software utility that converts a source program in a high-level

programming language, such as Basic, C or Pascal, into an object or compiled program in machine language. Compiled programs

run 10 to 1,000 times faster than interpreted programs

See also Interpreter.

conversion device device that transforms a signal from one form to another; for

example, analog-to-digital converters (ADCs) for analog input and digital-to-analog converters (DACs) for analog output

CPU central processing unit

CSYNC composite sync signal; a combination of the horizontal and

vertical sync pulses

CSYNCIN composite sync in signal

CSYNCOUT composite sync out signal

D

D/A digital-to-analog

DAC digital-to-analog converter; an electronic device, often an

integrated circuit, that converts a digital number into a

corresponding analog voltage or current

DAQ data acquisition—(1) collecting and measuring electrical signals

from sensors, transducers, and test probes or fixtures and inputting them to a computer for processing; (2) collecting and measuring the same kinds of electrical signals with A/D or DIO boards plugged into a computer, and possibly generating control signals with D/A and/or DIO boards in the same computer

dB decibel; the unit for expressing a logarithmic measure of the ratio

of two signal levels: dB=20log10 V1/V2, for signals in volts

DC direct current

default setting a default parameter value recorded in the driver; in many cases,

the default input of a control is a certain value (often 0) that means

use the current default setting.

DIN Deutsche Industrie Norme

DLL dynamic link library—a software module in Microsoft Windows

containing executable code and data that can be called or used by Windows applications or other DLLs; functions and data in a DLL are loaded and linked at run time when they are referenced by a

Windows application or other DLLs

DMA direct memory access—a method by which data can be transferred

to and from computer memory from and to a device or memory on the bus while the processor does something else; DMA is the fastest method of transferring data to/from computer memory

DRAM dynamic RAM

drivers software that controls a specific hardware device such as an

IMAQ or DAQ device.

dynamic range the ratio of the largest signal level a circuit can handle to the

smallest signal level it can handle (usually taken to be the noise

level), normally expressed in dB

E

EEPROM electrically erasable programmable read-only memory—ROM

that can be erased with an electrical signal and reprogrammed

external trigger a voltage pulse from an external source that triggers an event such

as A/D conversion

F

field For an interlaced video signal, a field is half the number of

horizontal lines needed to represent a frame of video; the first field of a frame contains all the odd-numbered lines, the second

field contains all of the even-numbered lines.

FIFO first-in first-out memory buffer—the first data stored is the first

data sent to the acceptor; FIFOs are used on IMAQ devices to temporarily store incoming data until that data can be retrieved. For example, an analog input FIFO stores the results of A/D conversions until the data can be retrieved into system memory, a process that requires the servicing of interrupts and often the programming of the DMA controller. This process can take several milliseconds in some cases. During this time, data

accumulates in the FIFO for future retrieval.

flash ADC an ADC whose output code is determined in a single step by a

bank of comparators and encoding logic

frame a complete image; in interlaced formats, a frame is composed of

two fields

front porch the area of a video signal between the start of the horizontal blank

and the start of the horizontal sync

ft feet

function a set of software instructions executed by a single line of code that

may have input and/or output parameters and returns a value when

executed; examples of functions are:

y = COS (x) status = AO_config(board, channel, range)

G

gamma the nonlinear change in the difference between the video signal's

brightness level and the voltage level needed to produce that

brightness

genlock circuitry that aligns the video timing signals by locking together

the horizontal, vertical, and color subcarrier frequencies and phases and generates a pixel clock to clock pixel data into memory for display or into another circuit for processing

GND ground signal

GUI graphical user interface—an intuitive, easy-to-use means of

communicating information to and from a computer program by means of graphical screen displays; GUIs can resemble the front panels of instruments or other objects associated with a computer

program.

Н

h hour

hardware the physical components of a computer system, such as the circuit

boards, plug-in boards, chassis, enclosures, peripherals, cables,

and so on

HSYNC horizontal sync signal—the synchronization pulse signal

produced at the beginning of each video scan line that keeps a video monitor's horizontal scan rate in step with the transmission

of each new line

HSYNCIN horizontal sync input signal

Hz hertz—the number of scans read or updates written per second

ı

IC integrated circuit

ID identification

IEEE Institute of Electrical and Electronics Engineers

IMAQconf a configuration and diagnostic utility included with IMAQ

devices

in. inches

INL integral nonlinearity—A measure in LSB of the worst-case

deviation from the ideal A/D or D/A transfer characteristic of the

analog I/O circuitry

interlaced a video frame composed of two interleaved fields; the number of

lines in a field are half the number of lines in an interlaced frame

instrument driver a set of high-level software functions, such as NI-IMAQ, that

controls specific plug-in computer boards; instrument drivers are available in several forms, ranging from a function callable from a programming language to a virtual instrument (VI) in LabVIEW

interpreter a software utility that executes source code from a high-level

language such as Basic, C or Pascal, by reading one line at a time

and executing the specified operation

See also compiler.

interrupt a computer signal indicating that the CPU should suspend its

current task to service a designated activity

interrupt level the relative priority at which a device can interrupt

I/O input/output—the transfer of data to/from a computer system

involving communications channels, operator interface devices,

and/or data acquisition and control interfaces

IRQ interrupt request

K

k kilo—the standard metric prefix for 1,000, or 10³, used with units

of measure such as volts, hertz, and meters

K kilo—the prefix for 1,024, or 2¹⁰, used with B in quantifying data

or computer memory

kbytes/s a unit for data transfer that means 1,000 or 10³ bytes/s

Kword 1,024 words of memory

L

library a file containing compiled object modules, each comprised of one

of more functions, that can be linked to other object modules that

make use of these functions.

line count the total number of horizontal lines in the picture

LSB least significant bit

LUT look-up table—a selection in the IMAQconf configuration utility

that contains formulas that let you implement simple imaging operations such as contrast enhancement, data inversion, gamma

manipulation, or other nonlinear transfer functions

M

m meters

M (1) Mega, the standard metric prefix for 1 million or 10⁶, when

used with units of measure such as volts and hertz; (2) mega, the prefix for 1,048,576, or 2^{20} , when used with B to quantify data or

computer memory

MB megabytes of memory

Mbytes/s a unit for data transfer that means 1 million or 10⁶ bytes/s

memory buffer See buffer.

memory window continuous blocks of memory that can be accessed quickly by

changing addresses on the local processor

MSB most significant bit

MTBF mean time between failure

mux multiplexer—a switching device with multiple inputs that

selectively connects one of its inputs to its output

N

NI-IMAQ driver software for National Instruments IMAQ hardware

noninterlaced a video frame where all the lines are scanned sequentially, instead

of divided into two frames as in an interlaced video frame

NTSC National Television Standards Committee—the committee that

developed the color video standard used primarily in North America, which uses 525 lines per frame. *See also* PAL.

NVRAM nonvolatile RAM—RAM that is not erased when a device loses

power or is turned off

0

operating system base-level software that controls a computer, runs programs,

interacts with users, and communicates with installed hardware or

peripheral devices

P

PAL Phase Alternation Line—one of the European video color

standards; uses 625 lines per frame. See also NTSC.

PCI Peripheral Component Interconnect—a high-performance

expansion bus architecture originally developed by Intel to replace ISA and EISA; it is achieving widespread acceptance as a standard for PCs and workstations and offers a theoretical

standard for PCs and workstations and offers a

maximum transfer rate of 132 Mbytes/s

PCLK pixel clock signal—times the sampling of pixels on a video line

PCLKIN pixel clock in signal

PFI programmable function input

PGIA programmable gain instrumentation amplifier

picture aspect ratio the ratio of the active pixel region to the active line region; for

standard video signals like RS-170 or CCIR, the full-size picture

aspect ratio normally is 4/3 (1.33)

pixel picture element—the smallest division that makes up the video

scan line; for display on a computer monitor, a pixel's optimum dimension is square (aspect ratio of 1:1, or the width equal to the

height)

pixel aspect ratio the ratio between the physical horizontal size and the vertical size

of the region covered by the pixel; an acquired pixel should optimally be square, thus the optimal value is 1.0, but typically it

falls between 0.95 and 1.05, depending on camera quality

pixel clock divides the incoming horizontal video line into pixels

pixel count the total number of pixels between two HYSNCs; the pixel count

determines the frequency of the pixel clock

PLL phase-locked loop—circuitry that provides a very stable pixel

clock that is referenced to another signal, for example, an

incoming HSYNC signal

protocol the exact sequence of bits, characters, and control codes used to

transfer data between computers and peripherals through a

communications channel

pts points

R

RAM random-access memory

real time a property of an event or system in which data is processed as it is

acquired instead of being accumulated and processed at a later

time

relative accuracy a measure in LSB of the accuracy of an ADC; it includes all

nonlinearity and quantization errors but does not include offset

and gain errors of the circuitry feeding the ADC

resolution the smallest signal increment that can be detected by a

measurement system; resolution can be expressed in bits, in proportions, or in percent of full scale. For example, a system has 12-bit resolution, one part in 4,096 resolution, and 0.0244 percent

of full scale.

ribbon cable a flat cable in which the conductors are side by side

ROI region-of-interest; a hardware-programmable rectangular portion

of the acquisition window

ROM read-only memory

RS-170 the U.S. standard used for black-and-white television

RTSIbus Real-Time System Integration Bus—the National Instruments

timing bus that connects IMAO and DAO boards directly, by

means of connectors on top of the boards, for precise

synchronization of functions

S

s seconds

scaling down circuitry circuitry that scales down the resolution of a video signal

scatter-gather DMA a type of DMA that allows the DMA controller to reconfigure

on-the-fly

SRAM static RAM

sync tells the display where to put a video picture; the horizontal sync

indicates the picture's left-to-right placement and the vertical

sync indicates top-to-bottom placement

syntax the set of rules to which statements must conform in a particular

programming language

system RAM RAM installed on a personal computer and used by the operating

system, as contrasted with onboard RAM

T

transfer rate the rate, measured in bytes/s, at which data is moved from source

to destination after software initialization and set up operations;

the maximum rate at which the hardware can operate

TRIG trigger signal

trigger any event that causes or starts some form of data capture

trigger control and mapping circuitry circuitry that routes, monitors, and drives the external and RTSIbus trigger lines; you can configure each of these lines to

start or stop acquisition on a rising or falling edge.

TTL transistor-transistor logic

V

V volts

VCO voltage-controlled oscillator—an oscillator that changes

frequency depending on a control signal; used in a PLL to

generate a stable pixel clock

VI Virtual Instrument—(1) a combination of hardware and/or

software elements, typically used with a PC, that has the

functionality of a classic stand-alone instrument (2) a LabVIEW software module (VI), which consists of a front panel user

interface and a block diagram program

video line a video line consists of a HSYNC, back porch, active pixel region,

and a front porch

VSYNC vertical sync signal—the synchronization pulse generated at the

beginning of each video field that tells the video monitor when to

start a new field

VSYNCIN vertical sync in signal

W

white reference level the level that defines what is white for a particular video system

See also black reference level.



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